

Elliptic Hamiltonian

Choose a Hamiltonian operator and orthogonal constraint in SU(3) defined by the matrices:

$$\tilde{H}(t) = \begin{pmatrix} 0 & \alpha(t) & 0 \\ \alpha(t) & 0 & -i\beta(t) \\ 0 & i\beta(t) & 0 \end{pmatrix} \quad \tilde{F}(t) = \begin{pmatrix} \omega_1(t) & -i\gamma(t) & \varepsilon(t) \\ i\gamma(t) & \omega_2(t) & \kappa(t) \\ \varepsilon^*(t) & \kappa(t) & \omega_3(t) \end{pmatrix}$$

where $\alpha, \beta, \gamma, \kappa, \omega_1, \omega_2, \omega_3$ are real functions of time and $\varepsilon(t)$ is a complex function of time.

These matrix operators obey the algebraic relations $\text{Tr}(\tilde{H}\tilde{F}) = \text{Tr}(\tilde{H}) = \text{Tr}(\tilde{F}) = 0$; we also have an isotropic constraint, given by $\text{Tr}(\tilde{H}^2/2) = \alpha^2(t) + \beta^2(t) = \text{const}$.

We have the quantum brachistochrone equation:

$$i \frac{d}{dt} (\tilde{H}(t) + \tilde{F}(t)) = \tilde{H}(t)\tilde{F}(t) - \tilde{F}(t)\tilde{H}(t)$$

Making the definition $\varepsilon(t) = \Omega(t) - i v(t)$ we obtain the system of differential equations given by:

$$\frac{d}{dt} \begin{pmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \end{pmatrix} = 2 \begin{pmatrix} \gamma\alpha \\ -(\gamma\alpha + \beta\kappa) \\ \beta\kappa \end{pmatrix}; \quad \frac{d}{dt} \begin{pmatrix} \gamma \\ \kappa \end{pmatrix} = \begin{pmatrix} -\beta v - (\omega_1 - \omega_2)\alpha \\ -\alpha v + (\omega_2 - \omega_3)\beta \end{pmatrix}$$

$$\frac{d}{dt} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = -i\Omega \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix}; \quad \frac{d}{dt} \begin{pmatrix} \Omega \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ \alpha\kappa + \beta\gamma \end{pmatrix}$$

which has a solution for the time-dependent Hamiltonian, given by the matrix:

$$\tilde{H}_{\text{opt}}(t) = R \begin{pmatrix} 0 & \cos(\Omega t + \theta) & 0 \\ \cos(\Omega t + \theta) & 0 & -i \sin(\Omega t + \theta) \\ 0 & +i \sin(\Omega t + \theta) & 0 \end{pmatrix}$$

Take a wave-vector, described by a superposition of time-dependent eigenvectors:

$$|\psi(t)\rangle = \Delta_1(t)|\rangle + R(t)|\rangle + \Delta_2(t)|0(t)\rangle + \Delta_3(t)|-R(t)\rangle$$

where

$$\tilde{H}(t)|J(t)\rangle = J|J(t)\rangle$$

Then our final state is given by the time-dependent vector:

$$|\psi(t)\rangle =$$

$$\begin{pmatrix} \cos(\Omega t + \theta)[z_3 \cos(\Omega' t) + (z_1/\Omega') \sin(\Omega' t)] - (\sin(\Omega t + \theta)/\Omega') [i(z_2 R/\Omega') + \Omega[(z_1/\Omega') \cos(\Omega' t) - z_3 \sin(\Omega' t)]] \\ 1/(\Omega'^2) [\Omega z_2 + i R(z_1 \cos(\Omega' t) - z_3 \sin(\Omega' t))] \\ -i[\sin(\Omega t + \theta)[z_3 \cos(\Omega' t) + (z_1/\Omega') \sin(\Omega' t)] + (\cos(\Omega t + \theta)/\Omega') [i(z_2 R/\Omega') + \Omega[(z_1/\Omega') \cos(\Omega' t) - z_3 \sin(\Omega' t)]] \end{pmatrix}$$

where the parameters are given by the formulae:

$$z_1 = \Omega \Delta_2(0) - i R \Delta_-(0); \quad z_2 = \Omega \Delta_-(0) - i R \Delta_2(0); \quad z_3 = \Delta_+(0)$$

$$\Delta_{\pm} = \frac{1}{\sqrt{2}} (\Delta_1 \pm \Delta_3) \quad \Omega' = +\sqrt{R^2 + \Omega^2}$$

The initial state is given by

$$|\psi(0)\rangle = \begin{pmatrix} z_3 \cos \theta - (\sin \theta) [\Omega z_1 + i R z_2] / \Omega'^2 \\ 1 / \Omega'^2 [\Omega z_2 + i R z_1] \\ -i [z_3 \sin \theta + (\cos \theta / \Omega'^2) [\Omega z_1 + i R z_2]] \end{pmatrix}$$

The question is then, given the form of the Hamiltonian operator as specified by the Quantum Brachistochrone, what is the functional form of the constraint $\tilde{F}(t)$?